

MHD (MAGNETO-HYDRODYNAMICS)

Relatively simple but useful model for the dynamics of fully ionized plasmas considering the plasma as a medium which follows the basic laws of continuum (equ. of continuity, momentum equ.) in addition to strong electromagnetic force.

Example: Earth's upper ionosphere, magnetosphere, solar plasma.

Assumptions:

Single fluid description

- Conducting fluid/magnetized continuum ($N_p \gg 1$)
implies \rightarrow large conductivity ($\sigma \propto N_p \cdot \omega_p$)
- Valid when plasma is collision dominated
implies \rightarrow distribution functions are locally Maxwellian (collision dominated charged species)
 - \rightarrow time scale " τ " large in MHD to allow collision, much larger than the time light takes to travel through the medium.
implies \rightarrow Displacement current in Maxwell's eqns can be neglected.
- \rightarrow length scale " L " is much larger than the mean free path between collisions.
 L is also larger than " λ_D "
 - \rightarrow fluid is quasi-neutral (i.e. $n_i = n_e = n$) which gives single fluid description

→ length scale $\lambda' \gg r_{Lo}$ (Larmor radius)
neglect

electron diamagnetism and Hall effects

in the electron momentum equ.

and electron inertia can be incorporated in
the ion momentum equ.

which allows

single fluid description

- charged species have the same temperature

→ combining with quasi-neutrality

pressure will be same

→ energy equilibrium time is short compared
to characteristic time scale " τ ".

IDEAL MHD

→ High conductivity

(1) CONTINUITY EQN. (NO SOURCE OR SINK)

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\vec{u} \rho) = 0$$

(2) MOMENTUM EQN. (FORCE EQN.)

$$\rho \left(\frac{\partial}{\partial t} \vec{u} + \vec{u} \cdot \nabla \vec{u} \right) = -\nabla p + \vec{j} \times \vec{B} + \rho \vec{g}$$

NAVIER STOKES Pressure magnetic force gravitational forces (Solar plasma)

Space time varying currents are important for the dynamics of the plasma because of very high conductivity.

IMPORTANT THING TO NOTICE:

NO CONTRIBUTION from the electric field due to charge separation.

$$\vec{F} = q\vec{E} + \vec{v} \times \vec{B} \rightarrow \text{single particle}$$

For fluid, (Force density) $\vec{f} = \rho_e \vec{E} + \vec{j} \times \vec{B} \rightarrow \text{quite important}$

charge density → This appears due to charge separation.

Due to high conductivity and large time scale it becomes negligible as it becomes quasi-neutral.

Now, we need to close these set of equations and find the expression for p , \vec{j} , \vec{B} and their space-time variations.

WHY POISSON'S EQN DOESN'T HELP MUCH HERE?

Assuming quasi-neutrality, $n_i = n_e$

Poisson's equ. $\nabla^2 \phi = -\frac{\rho}{\epsilon_0} (n_i - n_e)$

$= 0 \rightarrow$

At large scales

(3) FARADAY'S LAW

$$\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

Rotation of electric field equals to rate of change of magnetic field.

(4) AMPERE'S LAW:

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{j} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t} \rightarrow \text{Displacement current}$$

we neglect it in MHD

BUT HOW?

Let's assume,

the characteristic length scale in MHD = L wavelength of plane wave

and " " time scale " " = τ period of harmonic oscillator

Similarly, characteristic amplitude fluctuations in electric field = \tilde{E}_\perp

" " " " " magnetic field = \tilde{B}

Now using the characteristic quantities back in Ampere's Law we get,

$$\vec{\nabla}' \times \vec{B}' = \mu_0 \vec{J} \frac{L}{B} + \left(\frac{1}{c^2} \frac{\tilde{E}_\perp}{B} \frac{L}{\tau} \right) \frac{\partial}{\partial t'} \vec{E}'$$

Normalized form

LET'S FIND THE DETAILS:

$$c = \frac{1}{\sqrt{\mu_0 \epsilon_0}}$$

$$\nabla \rightarrow \frac{\partial}{\partial x} \rightarrow \frac{1}{L} \rightarrow \frac{1}{L}$$

$$\frac{\partial}{\partial t} \rightarrow \frac{1}{\tau} \rightarrow \frac{1}{\tau}$$

$$\vec{B}' = \frac{\vec{B}}{B}$$

$$\vec{E}' = \frac{\vec{E}}{E_\perp}$$

$$\frac{\tilde{E}_\perp}{B} \rightarrow \text{characteristic velocity } \left(\frac{\omega}{k} \right)$$

$$\frac{L}{\tau} \rightarrow \text{characteristic velocity}$$

Assuming the planar wave solution of the form,

$$f = f_{\text{amp}} e^{-i(\omega t - \vec{k} \cdot \vec{r})}$$

$$\vec{\nabla} \times \vec{E} \xrightarrow{\text{FFT}} i\vec{k} \times \vec{E} \rightarrow iE_{\perp}$$

$$\frac{\partial \vec{B}}{\partial t} \xrightarrow{\text{FFT}} -i\omega \vec{B}$$

using Faraday's law,

$$i\kappa E_{\perp} = i\omega B$$

$$\Rightarrow \frac{\omega}{\kappa} = \left| \frac{E_{\perp}}{B} \right|$$

Characteristic velocity. (\tilde{v})

$$\left(\frac{1}{c^2} \frac{\tilde{E}_{\perp}}{\tilde{B}} \frac{\omega}{\tau} \right) \rightarrow \frac{1}{c^2} \cdot \tilde{v}^2$$

$\tilde{v}^2 \ll c^2$
↓
slow phenomena

negligible → zero displacement current.

So the final form,

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{J}$$

CHALLENGE → COMBINE → $\vec{J}, \vec{E}, \vec{B}, \vec{u}$

(5) OHM'S LAW:

$$\vec{J} = \underline{\sigma} (\vec{E} + \vec{u} \times \vec{B})$$

External current \leftarrow (points to \vec{E})
 Neglecting the current due to moving net charge \leftarrow (points to $\vec{u} \times \vec{B}$)
 convective current \leftarrow (points to $\vec{u} \times \vec{B}$)
 MOVING FRAME OF REFERENCE \leftarrow (points to $\vec{u} \times \vec{B}$)
 Only comes from ABSOLUTE FRAME OF REFERENCE \leftarrow (points to $\underline{\sigma}$)

Due to the assumption of ideal conductor

$$\underline{\sigma} \rightarrow \infty$$

In ideal MHD as $\underline{\sigma} \rightarrow \infty$,

$$\vec{E} = -\vec{u} \times \vec{B}$$

For ideal MHD limit

\vec{E} is induced by the plasma moving across the magnetic field line.

Hence, within ideal MHD, electric fields cause no particle acceleration along magnetic field lines.

Since, all the fluctuations in the E-fields are in $\perp B$ direction, the velocity of a local fluid element can be expressed as

$$\vec{u} = \frac{\vec{E} \times \vec{B}}{B^2} \rightarrow \vec{E} = 0$$

In the rest frame of plasma.

(6) EQN OF STATE: Incompressible: $\vec{\nabla} \cdot \vec{u} = 0$

RECALLING MOMENTUM EQN.

$$p = f(\rho, T)$$

OPERATING $\vec{\nabla}$.

$$\frac{\partial \vec{u}}{\partial t} + \vec{u} \cdot \vec{\nabla} \vec{u} = -\frac{\vec{\nabla} p}{\rho}$$

Neutral fluid

$$\vec{\nabla} \cdot \left(\frac{\partial \vec{u}}{\partial t} \right) + \vec{\nabla} \cdot (\vec{u} \cdot \vec{\nabla} \vec{u}) = -\vec{\nabla} \cdot \frac{\vec{\nabla} p}{\rho}$$

$$\Rightarrow \vec{\nabla} \cdot \left(\frac{1}{\rho} \vec{\nabla} p \right) = -\vec{\nabla} \cdot (\vec{u} \cdot \vec{\nabla} \vec{u}) - \frac{\partial}{\partial t} (\vec{\nabla} \cdot \vec{u})$$

For Compressible:

$$\rho = \rho_0 \left(\frac{p}{p_0} \right)^{\gamma}$$

$$\Rightarrow \vec{\nabla} \cdot \left(\frac{1}{\rho} \vec{\nabla} p \right) = -\vec{\nabla} \cdot (\vec{u} \cdot \vec{\nabla} \vec{u})$$

Neutral fluid

$$\Rightarrow \vec{\nabla} \cdot \left(\frac{1}{\rho} \vec{\nabla} p \right) = -\nabla \cdot (\vec{u} \cdot \vec{\nabla} \vec{u}) + \nabla \cdot (\vec{j} \times \vec{B})$$

MHD

The equation of states for MHD defines the pressure independent of the history of the system for incompressible fluids.

no $\frac{\partial}{\partial t}$

For IDEAL MHD: (FLUID MECHANICS + PRE MAXWELL ELECTROMAGNETISM)

$$\frac{\partial \vec{B}}{\partial t} = \vec{\nabla} \times (\vec{u} \times \vec{B}) \quad (\text{FARADAY'S LAW})$$

CONSERVATION OF MAGNETIC FLUX

$$\frac{\partial \rho}{\partial t} + \vec{u} \cdot \vec{\nabla} \rho = 0$$

CONTINUITY EQN (incompressible)

$$\vec{\nabla} \cdot \vec{u} = 0$$

CONSERVATION OF MASS

$$\rho \left(\frac{\partial}{\partial t} \vec{u} + \vec{u} \cdot \vec{\nabla} \vec{u} \right) = -\nabla p + \frac{1}{\mu_0} [\vec{\nabla} \times \vec{B}] \times \vec{B}$$

AMPERE'S LAW

CONSERVATION OF MOMENTUM

For compressible, $p = f(\rho)$ and need to modify continuity equ.

INTERESTING PHENOMENA IN MHD

→ unstable motions

→ waves

→ sound waves → vibration of the fluids

→ Alfen waves → " " " magnetic field in presence of the fluid.

→ magnetosonic waves

→ coupling between fluid and the magnetic fields.