

MAGNETIC PRESSURE

MOMENTUM EQN:

$$\rho \left(\frac{\partial}{\partial t} \vec{u} + \vec{u} \cdot \nabla \vec{u} \right) = -\nabla p + \frac{1}{\mu_0} (\nabla \times \vec{B}) \times \vec{B} + \dots$$

Reorganizing the second term on the R.H.S. using vector algebra

$$\begin{aligned} \vec{B} \times (\nabla \times \vec{B}) &= (\nabla \cdot \vec{B}) \vec{B} - (\vec{B} \cdot \nabla) \vec{B} \\ &= \frac{1}{2} \nabla (\vec{B} \cdot \vec{B}) - (\vec{B} \cdot \nabla) \vec{B} \\ &= \frac{1}{2} \nabla B^2 - (\vec{B} \cdot \nabla) \vec{B} \end{aligned}$$

Now, let's rewrite the momentum equ.

$$\rho \left(\frac{\partial}{\partial t} \vec{u} + \vec{u} \cdot \nabla \vec{u} \right) = -\nabla \left(p + \frac{1}{2\mu_0} B^2 \right) + \frac{1}{\mu_0} (\vec{B} \cdot \nabla) \vec{B} + \dots$$

Magnetic field in the same mathematical form of plasma pressure.

In the context of MHD, in analogy to particle pressure the strength of the magnetic field will act in a similar way.

In general form,

$$\vec{J} \times \vec{B} = \frac{1}{\mu_0} (\nabla \times \vec{B}) \times \vec{B} = \nabla \cdot \Pi^M \rightarrow \text{Magnetic tensor}$$

$$\Pi^M = \frac{1}{\mu_0} \begin{bmatrix} B_x^2 - \frac{1}{2} B^2 & B_x B_y & B_x B_z \\ B_y B_x & B_y^2 - \frac{1}{2} B^2 & B_y B_z \\ B_z B_x & B_z B_y & B_z^2 - \frac{1}{2} B^2 \end{bmatrix}$$

We can simplify the form of magnetic tensor (π^M) by considering the following.

- i) The magnetic field lines are straight and parallel
- ii) The intensity of the magnetic field changes in \perp direction to \vec{B} .

This allows us to make $(\vec{B} \cdot \nabla) \vec{B} = 0$ which implies the total momentum comes from the pressure term.

$$\vec{j} \times \vec{B} = -\nabla \left(p + \frac{1}{2\mu_0} B^2 \right)$$

Now, additionally if we consider the magnetic field is $\parallel \hat{z}$,

$$\pi^M = \frac{1}{2\mu_0} \begin{bmatrix} -B^2 & 0 & 0 \\ 0 & -B^2 & 0 \\ 0 & 0 & B^2 \end{bmatrix}$$

↑ $\perp B$, magnetic pressure ↑ $\parallel B$, tension

Rewriting magnetic tensor in its general form,

$$\pi^M = \frac{1}{\mu_0} \begin{bmatrix} -\frac{1}{2} B^2 & 0 & 0 \\ 0 & -\frac{1}{2} B^2 & 0 \\ 0 & 0 & B^2 - \frac{1}{2} B^2 \end{bmatrix}$$

$$\pi^M = \frac{1}{\mu_0} \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & B_z^2 \end{bmatrix} - \frac{1}{2\mu_0} B^2 \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

TENSION along \hat{z}

isotropic pressure of magnetic field

Normal pressure,

$$\nabla p = \nabla(p \mathbb{1}) = \nabla \begin{pmatrix} p & 0 & 0 \\ 0 & p & 0 \\ 0 & 0 & p \end{pmatrix}$$

Similar representation

LOCAL PRESSURE

$\frac{B^2}{2\mu_0}$ is \perp to B-field lines

TENSION

$\frac{B_z^2}{2\mu_0}$ is \parallel to B-field lines

PLASMA β

Plasma β is the relative importance of plasma pressure with respect to magnetic pressure.

$$\beta = \frac{nkT}{B^2/2\mu_0}$$

← particle pressure / plasma pressure

← magnetic pressure

NOTE: β could be related to characteristic velocities as

$$\beta = \frac{C_s^2}{V_A^2} \left\{ \begin{array}{l} \leftarrow \text{sound speed} \\ \leftarrow \text{magnetic field (Alfven)} \end{array} \right.$$

In solar plasma

$$\beta = \{0.5, 1\}$$

Good interplay
between particle pressure
and magnetic pressure

In laboratory

$$\beta \sim 10^{-8}$$

Magnetic pressure largely
dominates in controlled
environment.

STATIONARY SOLUTION

Assuming $\vec{u} = 0$

The L.H.S. of our momentum equ. becomes zero. So, we have,

$$\nabla \left(p + \frac{1}{2\mu_0} B^2 \right) = \frac{1}{\mu_0} (\vec{B} \cdot \nabla) \vec{B}$$

Now, assume $\vec{B} \parallel \hat{z}$ and only variation is in \hat{x}

$$\Rightarrow B = [0, 0, B_z(x)], \quad p = p(x) \quad \text{Same for the pressure}$$

$$\nabla \left(p + \frac{1}{2\mu_0} B^2 \right) = \frac{d}{dx} \left(p + \frac{1}{2\mu_0} B^2 \right) = 0$$

$$\Rightarrow p + \frac{1}{2\mu_0} B^2 = \text{CONST.}$$

→ Plasma is
DIAMAGNETIC

i.e. if $p \uparrow$, then $B \downarrow$

Consider a large no. of particles and each of them are gyrating. Total contribution due to gyration will impact the external magnetic field. Increasing the no. of particle will reduce the magnetic pressure.

PLASMA PINCHES

It was introduced to confine plasma to make it sustainable.

IMPORTANT FEATURES!

- They are generally studied in cylindrical coordinate.
- No radial component of B , $B_r = 0$
- p, B do not depend on $\hat{z}, \hat{\theta}$

So, \vec{B} is expressed as,

$$\vec{B} = B_\theta(r) \hat{\theta} + B_z(r) \hat{z}$$

General Current expression

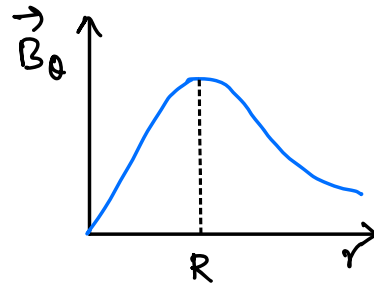
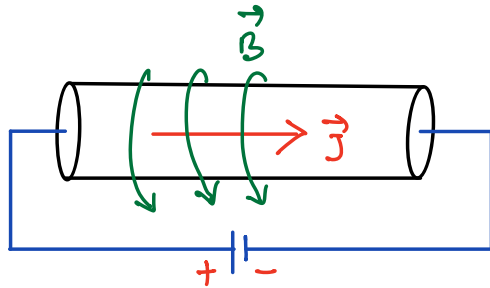
Using Ampere's law: $\vec{\nabla} \times \vec{B} = \mu_0 \vec{J}$

$$\vec{J} = \frac{1}{\mu_0} \left\{ 0, -\frac{dB_z}{dr}, \frac{1}{r} \frac{d(rB_\theta)}{dr} \right\}$$

Z-pinch

$$B_z = 0, \quad B = \{0, B_\theta, 0\}$$

Current only in z direction.



Theta-pinch

$$B = \{0, 0, B_z(r)\}$$

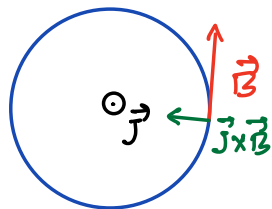
This will have purely azimuthal currents. (Theta direction)

SCREW pinch

Combination of Theta pinch + Z pinch

PINCH INSTABILITIES

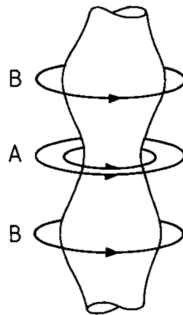
Considering different pinch axes, a small perturbation in current could lead to exponentially large variation making the system unstable.



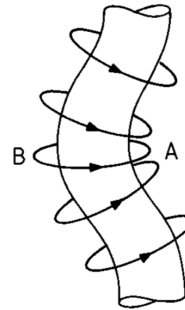
The pinch mechanism was supposed to confine the plasma using $\vec{j} \times \vec{B}$ force.

Two examples of different perturbations leading to instabilities.

Mag. pressure
 $A > B$



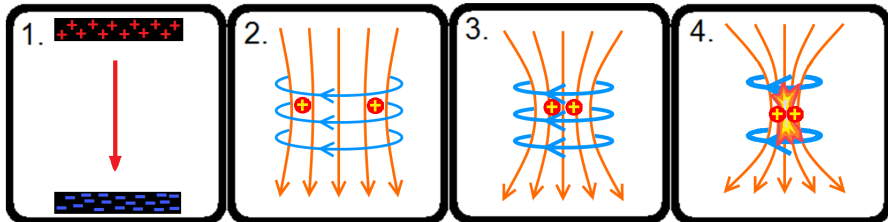
SASUAGE
INSTABILITY



Mag. pressure
 $A > B$

KINK
INSTABILITY

APPLICATION OF PMCH IN FUSION



Voltage Current Magnetic Field Ion