

Here, we are going to use the linearization technique by introducing small perturbation.

D Let's assume our steady state solutions are in the following form,

 $\vec{B} = B_0 \vec{z}$ ,  $\vec{f} = \vec{f}_0$ ,  $\vec{p} = \vec{p}_0$ ,  $\vec{u} = 0$ 

PERTURBATION!

 $\vec{B} = \vec{B}_0 + \vec{B}_1$ ,  $\vec{u} = 0 + \vec{u}_1$ ,  $\vec{\beta} = \vec{\beta}_0 + \vec{\beta}_1$ ,  $\vec{p} = \vec{\beta}_0 + \vec{p}_1$  $\vec{B}_0 >> \vec{B}_1$  and similar for all the quantities.

3 LINEARIZATION: (Ouly linear terms will survive)

Now, substituting the perturbed quantities in the main set of equs. and ignoring higher order terms (similar to the DYNAMIC Solutions we leaved) earlier

After linearization,

$$\frac{\partial}{\partial t} \vec{B}_{1} = \vec{\nabla} \times (\vec{u}_{1} \times \vec{B}_{0})$$

$$\frac{\partial}{\partial t} \vec{F}_{1} = 0$$

$$\vec{\nabla} \cdot \vec{u}_{1} = 0$$

$$\vec{S}_{0} \frac{\partial}{\partial t} \vec{u}_{1} = -\nabla \vec{F}_{1} + \frac{1}{M_{0}} (\vec{\nabla} \times \vec{B}_{1}) \times \vec{B}_{0}$$

(4) Assumption: The plasma supports wave like motion and have a form  $\exp[-i(\omega t - \vec{\kappa} \cdot \vec{r})]$ 

$$\begin{pmatrix} \vec{B}_{1} \\ \vec{u}_{1} \\ \vec{P}_{1} \\ \vec{P}_{1} \\ \vec{P}_{1} \end{pmatrix} = \begin{pmatrix} \vec{B}_{1} \\ \vec{u}_{1} \\ \vec{P}_{1} \\ \vec{P}_{1} \end{pmatrix} e^{-i(\omega t - \vec{k} \cdot \vec{r})} e^{-i(\omega t - \vec{k} \cdot \vec{r})}$$

(2)

It will allow us to rewrite the time and spatial derivatives in spectral form,

$$\frac{\partial}{\partial t} \rightarrow -i\omega \quad \vec{\nabla} \rightarrow i\vec{c}$$

5 Using the above expressions, we can rewrite our linearized equations,

$$-i\omega\vec{B}_{1} = i\vec{K} \times (\vec{u}_{1} \times \vec{B}_{0}) \stackrel{\text{using } BAC-CAB}{=} i(\vec{K} \cdot \vec{B}_{0})\vec{u}_{1} - i(\vec{K} \cdot \vec{u}_{1})\vec{E}_{0} \rightarrow (\vec{M})$$

$$-i\omega\vec{F}_{1} = 0 \rightarrow (\vec{M})$$

$$i\vec{K} \cdot \vec{u}_{1} = 0 \rightarrow (\vec{M})$$

$$-i\vec{f}_{0}\omega\vec{u}_{1} = -i\vec{K}\vec{F}_{1} + \frac{i}{M_{0}}(\vec{K} \times \vec{F}_{1}) \times \vec{E}_{0} \rightarrow (\vec{F})$$

Assuming K is real and W complex, we can write from the incompressibility condition,

(3) → KLU, i.e. the wave vector is L to the fluctuations in velocity. (TRANSVERIE)

Our continuity eqn. gives up (2)  $\rightarrow P_1 = 0$  which also make sense because of our incompressibility.

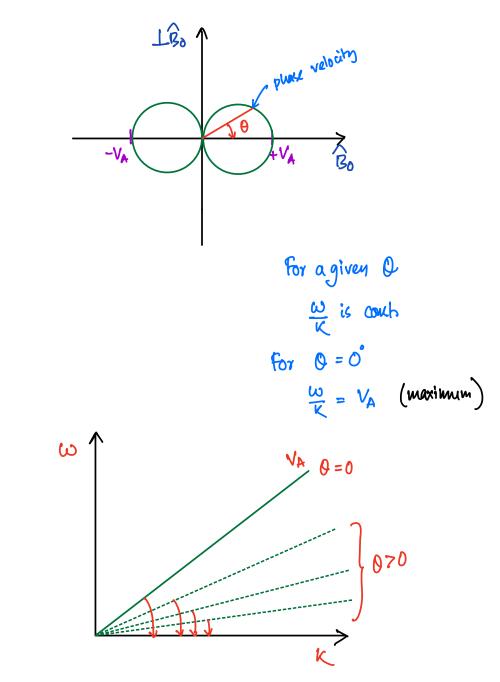
LITTLE RACKGROUND We had,  $\frac{\partial}{\partial t} f_1 = 0 = f_1 = const.$ Now,  $w \neq 0$ , to satisfy equ. (2) only logical choice for  $f_1 = 0$ 

Now, in equ. (1), the second term on R.H.S.  
(1) = 
$$-i\omega \vec{E}_1 = i(\vec{K} \cdot \vec{E}_0)\vec{U}_1 - i(\vec{K} \cdot \vec{U}_1)\vec{E}_0$$
  
=  $-i\omega \vec{E}_1 = i(\vec{K} \cdot \vec{E}_0)\vec{U}_1 \rightarrow \vec{E}_1$   
implies perturbations in  $\vec{E}$  are parallel to perturbations in  $\vec{U}$   
The magnetic field will oscillate  
in a proportion to the velocity vector  
in a direction  $\perp$  to  $\vec{E}_0$   
Betspread  
way. Field  
(4) =) Let's take the second term on RHS  
 $-\vec{E}_0 \times (\vec{K} \times \vec{E}_1)] = -\vec{K} (\vec{E}_0 \cdot \vec{E}_1) - \vec{E}_1 (\vec{E}_0 \cdot \vec{K})]$   
putting it back in (2) and multiplying i on both sides  
 $\vec{E}_0 = \vec{K} \cdot \vec{E}_0 = \vec{K} \cdot \vec{E}_0 = \vec{E}_1 + \vec{E}_0 (\vec{E}_0 \cdot \vec{E}_1) - \vec{E}_1 (\vec{E}_0 \cdot \vec{K})]$   
Now, using (5)  
 $\vec{E}_1 = -\vec{K} \cdot \vec{E}_0 = \vec{U}_1 = implies, \vec{E}_1 \cdot 1 \cdot \vec{U}_1$   
Again (6) -)  $\omega_{p_0} \vec{U}_1 = \vec{K} \cdot \vec{P}_1 + \frac{1}{M_0} (\vec{E}_0 \cdot \vec{E}_1) + \frac{1}{M_0} (\vec{E}_0 \cdot \vec{E}_1)^T \vec{U}_1$ 

## REARPANGING

$$\begin{split} \begin{split} & \left[ \begin{array}{c} \omega_{f_{0}} - \frac{1}{M_{0}\omega} \left( \vec{k} \cdot \vec{B}_{0} \right)^{T} \right] \vec{u}_{1} = \left[ \begin{array}{c} P_{1} + \frac{1}{M_{0}} \vec{B}_{0} \cdot \vec{B}_{1} \right] \vec{k} \\ \end{array} \\ & \text{Now, we already close } \vec{k} \text{ to be real and we have } \\ & \text{the same freedom to close } \vec{u}_{1} \text{ to be real. Hence,} \\ & \text{the only way the above equ. (7) is valid, if the } \\ & \text{individeal coefficients are 2ero.} \\ \\ & \omega_{f_{0}}^{2} - \frac{1}{M_{0}\omega} \left( \vec{k} \cdot \vec{B}_{0} \right)^{T} = 0 \\ & \Rightarrow \\ & \begin{array}{c} \omega_{f_{0}}^{2} - \frac{1}{M_{0}\omega} \left( \vec{k} \cdot \vec{B}_{0} \right)^{T} = 0 \\ \\ & \Rightarrow \\ \end{array} \\ & \begin{array}{c} \omega_{f_{0}}^{2} - \frac{1}{M_{0}f_{0}} \left( \vec{k} \cdot \vec{B}_{0} \right)^{T} \\ & \text{consequence of Frozen-IN-FIELD Lives} \\ \end{array} \\ & \begin{array}{c} \omega_{r}^{2} = \frac{1}{M_{0}f_{0}} \left( \vec{k} \cdot \vec{B}_{0} \right)^{T} \\ \\ & = 1 \\ \end{array} \\ & \begin{array}{c} \omega_{r}^{2} = \frac{1}{M_{0}f_{0}} \left( \vec{k} \cdot \vec{B}_{0} \right)^{T} \\ \\ & \end{array} \\ & \begin{array}{c} \varphi_{r} = \frac{1}{M_{0}f_{0}} \left( \vec{k} \cdot \vec{B}_{0} \right)^{T} \\ \\ & \varphi_{r} = \frac{1}{M_{0}f_{0}} \left( \vec{k} \cdot \vec{B}_{0} \right)^{T} \\ \end{array} \\ & \begin{array}{c} \varphi_{r} = \frac{1}{M_{0}f_{0}} \left( \vec{k} \cdot \vec{B}_{0} \right)^{T} \\ \\ & \end{array} \\ & \begin{array}{c} \varphi_{r} = \frac{1}{M_{0}f_{0}} \left( \vec{k} \cdot \vec{B}_{0} \right)^{T} \\ \end{array} \\ & \begin{array}{c} \varphi_{r} = \frac{1}{M_{0}f_{0}} \left( \vec{k} \cdot \vec{B}_{0} \right)^{T} \\ \\ & \end{array} \\ & \begin{array}{c} \varphi_{r} = \frac{1}{M_{0}f_{0}} \left( \vec{k} \cdot \vec{B}_{0} \right)^{T} \\ \end{array} \\ & \begin{array}{c} \varphi_{r} = \frac{1}{M_{0}f_{0}} \left( \vec{k} \cdot \vec{B}_{0} \right)^{T} \\ \end{array} \\ & \begin{array}{c} \varphi_{r} = \frac{1}{M_{0}f_{0}} \left( \vec{k} \cdot \vec{B}_{0} \right)^{T} \\ \end{array} \\ & \begin{array}{c} \varphi_{r} = \frac{1}{M_{0}f_{0}} \left( \vec{k} \cdot \vec{B}_{0} \right)^{T} \\ \end{array} \\ & \begin{array}{c} \varphi_{r} = \frac{1}{M_{0}f_{0}} \left( \vec{k} \cdot \vec{B}_{0} \right)^{T} \\ \end{array} \\ & \begin{array}{c} \varphi_{r} = \frac{1}{M_{0}f_{0}} \left( \vec{k} \cdot \vec{B}_{0} \right)^{T} \\ \end{array} \\ & \begin{array}{c} \varphi_{r} = \frac{1}{M_{0}f_{0}} \left( \vec{k} \cdot \vec{B}_{0} \right)^{T} \\ \end{array} \\ & \begin{array}{c} \varphi_{r} = \frac{1}{M_{0}f_{0}} \left( \vec{k} \cdot \vec{B}_{0} \right)^{T} \\ \end{array} \\ & \begin{array}{c} \varphi_{r} = \frac{1}{M_{0}f_{0}} \left( \vec{k} \cdot \vec{B}_{0} \right)^{T} \\ \end{array} \\ \end{array} \\ & \begin{array}{c} \varphi_{r} = \frac{1}{M_{0}f_{0}} \left( \vec{k} \cdot \vec{B}_{0} \right)^{T} \\ \end{array} \\ \end{array} \\ & \begin{array}{c} \varphi_{r} = \frac{1}{M_{0}f_{0}} \left( \vec{k} \cdot \vec{B}_{0} \right)^{T} \\ \end{array} \\ \end{array} \\ \end{array}$$
 \\ & \begin{array}{c} \varphi\_{r} = \frac{1}{M\_{0}f\_{0}} \left( \vec{k} \cdot \vec{B}\_{0} \right)^{T} \\ \end{array} \\ \end{array} \\ & \begin{array}{c} \varphi\_{r} = \frac{1}{M\_{0}f\_{0}} \left( \vec{k} \cdot \vec{B}\_{0} \right)^{T} \\ \end{array} \\ \end{array} \\ \end{array}

We also have,  $\vec{u_1} \perp \vec{k}$  (from incomprescibility) implies, the waves are transverse and referred as SHEAR ALFVEN Wave.



GROUP VELOCITY (ENERGY)

$$\frac{\partial \omega}{\partial k} = \nabla_{k} \omega$$

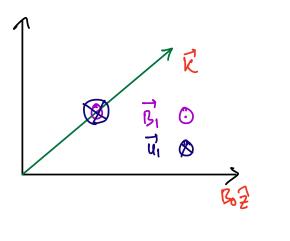
$$\omega^{2} = V_{A}^{2} K_{z}^{2} \quad \text{Considering, } \vec{B_{0}} = 8_{0} \hat{z}$$

$$\Rightarrow \omega = \pm V_{A} K_{z}$$

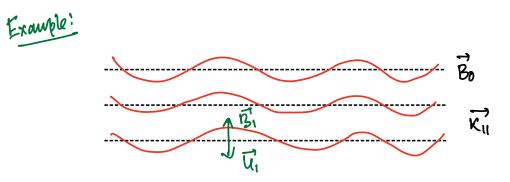
$$\Rightarrow \nabla_{k} \omega = \pm V_{A} \hat{z}$$

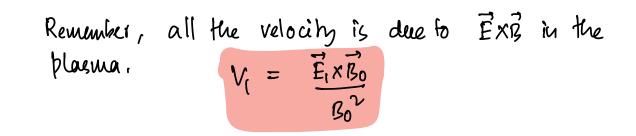
important thing to notice, the group velocity does not depend ou is instead it is always along the background magnetic field Bo. Therefore, the propagation of information and energy is always along the background magnetic field line. Now, let's get back to equ. 7 Considering the Coefficient ou R.H.S.  $\left| \dot{P}_{1} + \frac{1}{M_{0}} \vec{B}_{0} \vec{B}_{1} \right| = 0$ =)  $p_1 = -\frac{1}{M_0} \overrightarrow{B_0} \overrightarrow{B_1}$ We also have,  $\vec{B}_1 = -\vec{k} \cdot \vec{B}_0 \vec{u}_1$  $P_{I} = \frac{1}{M_{0}} \left( \vec{B}_{0} \cdot \vec{K} \right) \left( \vec{B}_{0} \cdot \vec{U}_{I} \right) \rightarrow \Re$ 

This is equivalent to EQN. OF STATE for incompressible MHD.



If we have 
$$\vec{B}_1, \vec{u}_1 \perp$$
  
plane  $\vec{k}$  and  $\vec{B}_0$   
 $\vec{p} = 0$   
=) SHEAR ALFVEN WAVES





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ENERGY DENSITY FOR SHEAR ALFVEN WAVE

Ratio of electric and magnetic field energy,  

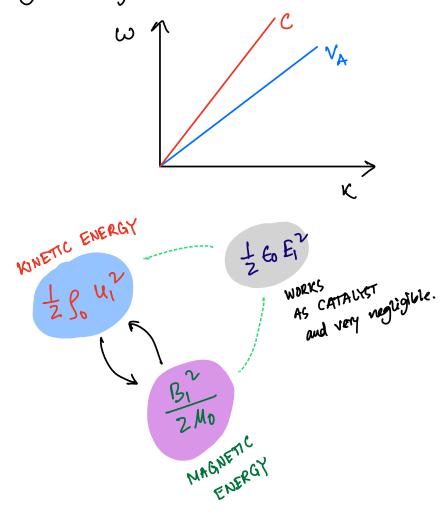
$$\frac{WE}{WE} = \frac{1}{2} \frac{\mathcal{E}_0 |E_1|^2}{\frac{1}{2}} = \frac{|E_1|^2}{|B_1|^2} \frac{1}{C^2}, \text{ where } C^2 = \frac{1}{M_0} \frac{1}{M_0}$$

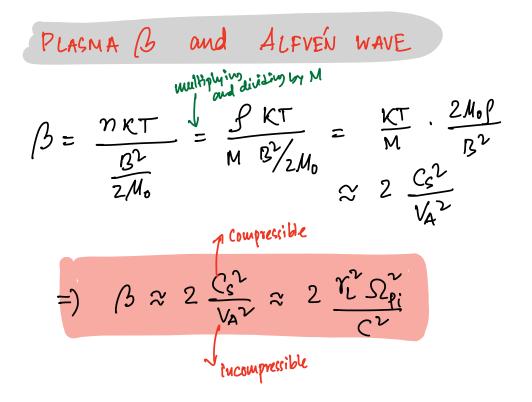
For SHEAR ALFVE'N WAVE,

$$\vec{k} \perp \vec{E}_{1} = \frac{1}{2} \frac{1}{|B_{1}|} = \frac{\omega}{k} = V_{A}$$

$$= \frac{W_{E}}{W_{g}} = \frac{V_{A}}{C^{2}} < 1$$

Therefore, the electric energy is negligible in comparison to magnetic field energy.





The assumption of incompressibility also assumes that  
all velocities of propagation are well below sound speed.  
Which means, 
$$\beta >>1$$
  
But in practical  $\beta <<1$  or  $\beta \approx 1$ . Therefore,  
we may need to think about  $V_4$ .